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मानक

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IS 8214-1 (1976): Glossary of ships' hydrodynamic terms,
Part 1 Basic quantities [TED 17: Shipbuilding]



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Bhartrhari—Nitiśatakam

“Knowledge is such a treasure which cannot be stolen”

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IS : 8214 (Part I) - 1976

Indian Standard
**GLOSSARY OF SHIPS'
HYDRODYNAMIC TERMS**

PART I BASIC QUANTITIES

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NEW DELHI 110002

AMENDMENT NO. 1 DECEMBER 1977
TO
IS : 8214 (Part I) - 1976 GLOSSARY OF SHIPS'
HYDRODYNAMIC TERMS
PART I BASIC QUANTITIES

Corrigenda

(*Page 3, clause 0.2, line 4*) — Substitute 'ease' for 'case'.

(*Page 5, informal table, second column, against Sl No. 2.27*) —
Substitute 'Q' for 'O'.

(*Page 7, informal table, fourth column, against Sl No. 2.48*) —
Substitute the following for the existing equation:

$$F (t) = A e^{-\delta t} \sin \frac{2\pi (t - t_0)}{T}$$

(MCPD 1)

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Indian Standard

GLOSSARY OF SHIPS' HYDRODYNAMIC TERMS

PART I BASIC QUANTITIES

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(Continued on page 2)

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IS : 8214 (Part I) - 1976

(Continued from page 1)

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Indian Standard
GLOSSARY OF SHIPS'
HYDRODYNAMIC TERMS
PART I BASIC QUANTITIES

0. FOREWORD

0.1 This Indian Standard (Part I) was adopted by the Indian Standards Institution on 30 September 1976, after the draft finalized by the Shipbuilding Sectional Committee had been approved by the Marine, Cargo Movement and Packaging Division Council.

0.2 The object of this standard is to specify the technical and scientific terms used in ship geometry, hydrostatics and hydrodynamics and to facilitate the exchange of information, particularly at international level, and the ease of understanding as regards to documents relating to naval architecture.

0.3 The terms are represented by symbols which have been arranged in alphabetical order for ease of interpretation.

0.4 No rules are laid down as to whether subscripts are to be shown by capital or lower case letters, although the letters shown in this standard are in the preferred style.

0.5 When required, the suffixes M and S should be introduced to distinguish between quantities referring to model and ship respectively.

0.6 For guidance, a complete list of Greek alphabets is given in Appendix A.

0.7 This standard is being issued in six parts. The other parts in the series are:

- Part II Ship geometry
- Part III Resistance and propulsion
- Part IV Sea keeping
- Part V Manoeuvrability
- Part VI Strength and vibration

IS: 8214 (Part I) - 1976

0.3 While preparing this standard, current work by ISO/TC 8 on 'Terminology of Profiles and Hydrodynamic Terms' and International Towing Tank Conference (I.T.T.C) has also been considered.

1. SCOPE

1.1 This standard (Part I) deals with basic quantities used in ships' hydrodynamic terms.

2. TERMINOLOGY

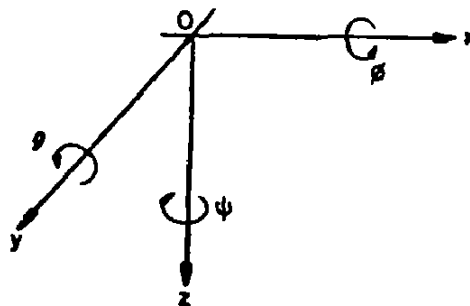
Sl No.	SYMBOL	TERMS	DEFINITIONS	SYMBOL OF SI UNITS
2.1	a	Linear acceleration	$\frac{dv}{dt}$	ms^{-2}
2.2	A	Area in general	—	m^2
2.3	A_T	Cross-sectional area of an experiment tank or tunnel	—	m^2
2.4	B	Breadth in general	—	m
2.5	c	Velocity of sound	—	ms^{-1}
2.6	D, d	Diameter in general	—	m
2.7	E	Energy in general	—	Nm
2.8	F	Force in general	—	N
2.9	f	Frictional coefficient	Ratio of tangential force to normal force between two sliding bodies or planes	—
2.10	g	Acceleration due to gravity	—	ms^{-2}
2.11	h	Depth in general	—	m
2.12	h	Pressure head in general	—	m
2.13	ζ_w	Height of a wave	Vertical distance between the crest and trough of a surface wave	m
2.14	H_t	Total head, Bernoulli	$h + \frac{p}{w} + \frac{q}{w}$	m

IS : 8214 (Part I) - 1976

Sl. No.	Symbol	Term	Definitions	Symbol of SI Units
2.15	K_s	Sand roughness	Mean diameter of the equivalent sand grains covering a surface	m
2.16	L	Length in general	—	m
2.17	L_w, λ	Wave length	Length between two successive similar points of the wave profile in the direction of propagation, for instance, between successive troughs	m
2.18	m	Mass	—	kg
2.19	M	Moment in general	—	Nm
2.20	n	Rate of revolution	—	s^{-1}
2.21	p	Pressure intensity in general	Force per unit area	Nm^{-2}
2.22	p_c	Cavitation pressure	Pressure at the cavitation start point	Nm^{-2}
2.23	p_v	Vapour pressure of water	—	Nm^{-2}
2.24	p_∞	Ambient pressure at infinity	—	Nm^{-2}
2.25	P	Power in general	$P = \frac{E}{t}$	W
2.26	q	Dynamic pressure	$\frac{1}{2}\rho U^2$	Nm^{-2}
2.27	Q	Rate of flow	Volume of fluid per unit time	$m^3 s^{-1}$
2.28	r, R	Radius in general	—	m
2.29	R_c	Radius of curvature	—	m
2.30	R_H	Radius, hydraulic	Area of section divided by wetted perimeter	m
2.31	s	Length along path	—	m
2.32	t	Time in general	—	s
2.33	t_o	Temperature in general	—	$^{\circ}C$

IS: 8214 (Part I) - 1976

Sl. No.	SYMBOL	TERMS	DEFINITIONS	SYMBOL OF SI UNITS
2.34	T	Period of time for a complete cycle	Time interval of a complete cycle of a periodical phenomenon	s
2.35	u, v, w	Velocity components in direction of x, y, z axes	—	ms^{-1}
2.36	U, V	Linear velocity	$\frac{ds}{dt}$	ms^{-1}
2.37	∇, V	Volume in general	—	m^3
2.38	w	Weight density	ρg	Nm^{-3}
2.39	W	Weight in general	—	N
2.40	x, y, z	Body axis and Cartesian co-ordinates	Right hand orthogonal system of axes fixed in the body with the z-axis vertically downwards. The x-axis forward and parallel to reference or base line used to determine body's shape. The origin should, in general, be at the centre of gravity of the body, any other point used must be clearly defined	m



IS : 8214 (Part I) - 1976

Sl. No.	SYMBOL	TERMS	DEFINITIONS	SYMBOL OF SI UNITS
2.41	x_0, y_0, z_0	Fixed axes and corresponding Cartesian co-ordinates	Right hand orthogonal system of axes nominally fixed in relation to the earth, the positive z_0 -axis is vertically downwards and the x_0 -axis lies in the general direction of initial motion	m
2.42	α	Coefficient of thermal expansion (linear)	Elongation per unit length per degree change in temperature	K^{-1}
2.43	α	Angular acceleration	$\frac{d\omega}{dt}$	rad s^{-2}
2.44	γ	Specific gravity	Weight of a substance divided by the weight of an equal volume of distilled water at 4°C	—
2.45	γ	Adiabatic exponent	—	—
2.46	Γ	Circulation	$\oint \vec{V} \cdot d\vec{s}$, along a closed line	$\text{m}^2 \text{s}^{-1}$
2.47	δ	Thickness of a boundary layer in general	—	m
2.48	δ	Damping coefficient	When F is a function of time given by $F(t) = Ae^{-\delta t} \sin \frac{2\pi(t-t_0)}{T}$ δ is the damping coefficient	—

IS : 8214 (Part 1) - 1976

Sl No.	SYMBOL	TERMS	DEFINITIONS	SYMBOL OF SI UNITS
2.49	θ	Angle of trim or pitch	Static (trim) or dynamic (pitch) angular displacement about y-axis, of base line from its initial reference position	—
2.50	κ	Coefficient of kinematic capillarity	$\frac{\sigma}{\rho}$	$\text{m}^3 \text{s}^{-2}$
2.51	μ	Coefficient of dynamic viscosity	Shear stress per unit velocity gradient	Ns m^{-2}
2.52	ν	Coefficient of kinematic viscosity	$\frac{\mu}{\rho}$	$\text{m}^2 \text{s}^{-1}$
2.53	ρ	Mass density	Mass per unit volume	kg m^{-3}
2.54	σ	Capillarity coefficient	Surface tension per unit length	Nm^{-1}
2.55	ϕ	Potential function such as velocity potential	$u = \frac{\delta\phi}{\delta x}, \quad v = \frac{\delta\phi}{\delta y},$ $w = \frac{\delta\phi}{\delta z}$	$\text{m}^2 \text{s}^{-1}$
2.56	ϕ	Angle of roll, heel or list	Static (heel) or dynamic (roll) angular displacement, about x-axis, of the plane of symmetry from its initial reference position	—
2.57	Ψ	Stream function	$\Psi = \text{Const.}$ is the equation of a stream line	$\text{m}^3 \text{s}^{-1}$
2.58	Ψ	Angle of yaw	Dynamic angular displacement about z-axis of the plane of symmetry from its initial reference position	—
2.59	ω	Angular velocity or circular frequency	Angle per unit time	rad s^{-1}

APPENDIX

(Clause 0.6)

GREEK ALPHABETS

A	α	alpha	N	ν	nu
B	β	beta	Ξ	ξ	xi
Γ	γ	gamma	O	\omicron	omicron
Δ	δ	delta	Π	π	pi
E	ϵ	epsilon	P	ρ	rho
Z	ζ	zeta	Σ	σ	sigma
H	η	eta	T	τ	tau
Θ	θ	theta	Υ	υ	upsilon
I	ι	iota	Φ	ϕ	phi
K	κ	kappa	X	χ	chi
Λ	λ	lambda	Ψ	ψ	psi
M	μ	mu	Ω	ω	omega

INTERNATIONAL SYSTEM OF UNITS (SI UNITS)

Base Units

Quantity	Unit	Symbol
Length	metre	m
Mass	killogram	kg
Time	second	s
Electric current	ampere	A
Thermodynamic temperature	kelvin	K
Luminous intensity	candela	cd
Amount of substance	mole	mol

Supplementary Units

Quantity	Unit	Symbol
Plane angle	radian	rad
Solid angle	steradian	sr

Derived Units

Quantity	Unit	Symbol	Conversion
Force	newton	N	1 N = 1 kg. 1 m/s ²
Energy	joule	J	1 J = 1 N.m
Power	watt	W	1 W = 1 J/s
Flux	weber	Wb	1 Wb = 1 V.s
Flux density	tesla	T	1 T = 1 Wb/m ²
Frequency	hertz	Hz	1 Hz = 1 c/s (s ⁻¹)
Electric conductance	siemens	S	1 S = 1 A/V
Pressure, stress	pascal	Pa	1 Pa = 1 N.m ⁻²

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